Audiovisual Correspondence Learning in Humans And Machines

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Abstract

Audiovisual correspondence learning is the task of acquiring the association between images and its corresponding audio. In this paper, we propose a novel experimental paradigm in which unfamiliar pseudo images and pseudo words in audio form are introduced to both humans and machine systems. The task is to learn the association between the pairs of image and audio which is later evaluated with a retrieval task. The machine system used in the study is pre-trained with the image-net corpus along with the corresponding audio labels. This model is transferred for the new image-audio pairs. Using the proposed paradigm, we perform a direct comparison of one-shot, two-shot and three-shot learning performance for humans and machine systems. The human behavioral experiment confirms that the percentage of the correspondence learning happens in the first exposure of the audio-visual pair. This paper proposes a machine model which performs on par with the humans in audio-visual correspondence learning. But compared to the machine model, humans exhibited better generalization ability for new input samples with a single exposure.

Index Terms: Audiovisual correspondence learning, few-shot learning, multimodal learning, transfer learning, human-machine comparison

1. Introduction

The fusion of multi-modal signals, i.e., signals measured in multiple domains, has been an area of considerable interest for both humans [1] and machines [2]. In this paper, we consider a type of fusion problem that pertains to learning how different modalities correspond to each other. The modalities under consideration are audio and image domains.

In human cognition, cross-modal correspondence learning can be defined as the learning of the mapping that observers expect to exist between two or more features or dimensions from different sensory modalities (such as shape of the visual object and associated speech phonemes) [3]. Once the learning is achieved, stimulation in one modality can elicit experiences in the other sensory modality (for example, sound-color associations [4]) which can also extend to behavioral changes and cross-modal retrieval [5]. However, many questions exist on how efficient humans are in learning object-audio associations for previously unknown shapes and sounds. In this paper, we attempt to highlight the behavioral performance for human subjects in learning cross-modal audio-visual correspondences for pseudo images and pseudo-words. We also analyze the ability of humans to generalize to different orientations and color changes of the visual objects as well as the speaker changes in the speech data. Past studies have shown that humans require only a very small number of instances to learn meanings of new words [6].

It is therefore of significant interest to question whether machines can achieve human level efficiency with limited data. In machine learning, cross-modal correspondence modeling and retrieval has received significant attention in recent years, in particular between domains of text and image [7]. For audio-visual cross-modal modeling, early work by Zhang et. al. [8] focused on correlation based modeling. Recent work using deep learning by Arandjelovic et. al. [2] attempted to learn the association between audio and images in an unsupervised manner using video data. In a similar vein, development of algorithms for cross-modal data generation has also been attempted recently [9]. In our previous work [10], we explored a rapid language learning task where human subjects attempt to learn a set of words from a new language with image supervision. A machine comparison for this task revealed that machines can achieve human level performance for this task on previously known image classes.

In this paper, we explore a learning paradigm where novel objects and novel sounds are associated. This novelty is critical for ensuring a direct human machine comparison as the novelty guarantees that we are not merely tapping into knowledge acquired prior to the experiment in humans. The pseudo object images were derived from the novel object and unusual names (NOUN) dataset [11]. The images in the NOUN Database depict multi-part, multicolored, real three-dimensional (3-D) objects, as opposed to simple geometric shape configurations. The unknown names in the dataset were converted to speech using a speech synthesis software. The audio and visual stimuli were provided jointly to learn the association. We performed experiments with one-shot, two-shot and three-shot learning for humans and machines.

2. Human Experiment

2.1. Stimuli

The objects and labels used are primarily from the Novel Object and Unusual Name (NOUN) Database [11]. The NOUN dataset contains 60 novel objects, and 173 pseudo words. We used the 60 objects as our novel classes and paired it with a pseudo word label. The label is a trisyllabic pseudo word generated by combining the original NOUN pseudo words. The original images from the NOUN data-set were augmented by performing RGB permutations, horizontal and vertical flipping, and rotations. For each object class, 10 such augmented variants of the original image were added to the stimuli set. The examples of the stimuli used are given in Fig 1. We generated 12 audio samples per label from their synthesized speech, using Google [12], IBM [13], and Microsoft [14] Text-to-Speech (TTS) systems. These audio samples had variations as the TTS models with different gender and accents (American English, British English and Australian English) were used. An informal listening test of the files showed no major inconsistencies in pronunciation across the models.
The participants were Indian nationals with self-reported normal hearing and vision. Twenty four adults participated in this study (mean age = 24.08, age span = 22-31). All subjects provided written informed consent to take part in the experiment and received a monetary compensation. The Institute Human Ethical Committee of Indian Institute of Science, Bangalore approved all procedures of the experiment.

2.2. Subjects

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2.3. Experimental Setup

The stimuli were randomly divided into 6 blocks with 10 novel classes in each block. During the experiment, these blocks appeared in a different random order for different subjects. Each block was a n-shot learning paradigm of 10 novel objects \((n = 1, 2 \text{ or } 3)\). An n-shot learning task means the participant is exposed to n augmented variants of the stimulus before the evaluation. There were 2 blocks for each n-shot learning. The experiment starts with a practice session to familiarize participants with the experiment setup. The practice session used 3 objects as stimuli, which are not part of the main experiment. They were from the Fribbles stimuli set [15], and labels were sampled from the trisyllabic word pool. Each block in the main experiment had two phases: learning phase and testing phase.

Learning Phase: In the learning phase, the subjects were presented with image-audio pairs for each class in the session. Classes within a session were randomly shuffled. For the 2 and 3 shot sessions, the 10 classes were presented in cycles, in a random order within each cycle. No limit was imposed on the learning time per sample, or the number of times the audio clip could be heard. For each subject, we recorded the total time spent and number of audio play button clicks on each sample.

Testing Phase: During the testing phase, the subjects were asked to perform two tasks: an image retrieval (IR) and an audio retrieval (AR) task. In IR, the subject had to pick the matching image for the given audio sample from a set of 10 image choices. In AR, the subject had to pick the corresponding audio clip for the given image sample from a set of 10 audio choices. For each session, both tasks included 10 test cases (as each block had 10 novel objects to learn). The image and audio samples used in the test phase were augmented versions of its training counterparts. Further, one-shot learning blocks had an additional test case for each of the 10 objects showed in the training phase. In this testing case, the query sample was the exact same image/audio sample that appeared during the learning phase. Hence, the subject had already seen this exact sample before the evaluation. But the multiple-choice answer options include augmented versions of samples from the other modality. This strategy enables us to compare the generalisation capability of humans and machines on the one-shot task.

3. Machine Experiments

3.1. Dataset

For pre-training, we use the 655 classes from [10]. These classes have labels of one word length. Images are obtained from the Imagenet database [16], and the Flickr and Google image repository. The audio recordings of the labels are generated using the Google, Microsoft [14] and IBM [13] TTS systems.

For the novel object learning task, we use the same 60 novel classes as in the human experiment. The data split per class, as \((\text{train, test})\), is \((n, 10-n)\) for images with a total of 10 images per class. For audio, it is \((n, 12-n)\) with a total of 12 audio variants per class. Here, \(n = 1, 2\) or 3 for n-shot learning.

3.2. Audio-Visual Semantic Network

We use the joint audio-visual model [10] illustrated in Fig 2. It consists of audio and image sub-networks which are jointly trained on the multi-modal input.

Audio sub-network: The audio sub-network has two long short term memory (LSTM) layers followed by fully connected (FC) layers. The audio is fed as 80 dimensional bottleneck features, from a deep neural network trained for automatic speech recognition (ASR) on the switch-board and Fisher corpora [17]. After pre-training, only the final fully connected layer of 576 dimensions is trained on the novel audio labels.

Image sub-network: The image sub-network uses the Xception network [18] which is trained on the Imagenet classes. We use the 2048 dimensional pre-softmax layer from the Xception network as the input representation. This input is then mapped to a 576 dimensional latent space using a fully connected layer which is trained jointly with the audio sub-network.
3.3. Training

Pretraining: The 576 dimensional FC layers of the audio and image subnetworks are trained jointly on 655 pretraining classes. We use the modified proxy based approach of [19][10] to train using multimodal input. Similarity is maximized between the input representation and matching proxy vector, and minimized against the non-matching proxy vectors. In the first stage, the proxy matrix and FC layer of the image subnetwork are trained on the image data. The proxy matrix is then kept fixed. In the second stage, the FC layer of the audio subnetwork is trained using the audio data. We minimize the NCA loss for training [20] and train for 100 epochs with a learning rate of 0.001. We use the Adam optimizer with batch-norm and dropout. Results for retrieval on the pre-training classes are given in table 2.

Transfer Learning: The data for the novel classes is divided into blocks of 10 classes. Our machine setup is trained on the data of one block at a time to emulate the human experiment. For 2 and 3 shot learning, the data is repeated in cycles. Since the blocks contain novel independent objects and labels, we train and test each block separately and not in an incremental fashion. Like the human experiment, the order of classes is randomized. We use a triplet based approach for training, and maximize similarity between a matching image/audio pair while minimizing similarity between non-matching image/audio pairs. Similarity is given by:

\[ S_{j,k} = -\|y_j - x_k\|^2 \]  

where \( y_j \) and \( x_k \) are the L2 normalized embedding for image \( j \) and audio \( k \) respectively. The triplet loss is given by,

\[ C(\theta) = S_{a,n} - S_{a,p} + \alpha \]  

where \( \theta \) are the model parameters, \( a \) is the anchor point, \( p \) and \( n \) are the corresponding positive and negative points, and \( \alpha \) is the margin which we set at 0.8. The model is trained to convergence on one class before moving to the next. In 1-shot learning, the anchor and positive data samples are the image/audio samples used in the human experiment with negative data sampled from the pretraining classes. During the 2 and 3 shot learning phases, the anchor is the novel image/audio of the current cycle, positive points are sampled from the current and previous cycles, and negative points are sampled from the previous cycles and pretraining classes. We train on each novel class for 5 epochs with 4 batches per epoch of size 120, using a learning rate of 0.001. We use the Adam optimizer with batch-norm and dropout.

4. Results and Discussions

4.1. Human Experiment Results

4.1.1. Retrieval Scores

Fig. 3 shows the average score for each \( n \)-shot learning across all subjects as accuracy (%). For humans, both IR and AR scores in the 1, 2 and 3 shot blocks are in an ascending order. The overall AR accuracy is higher than that of IR, with means of 88.194 and 86.528 respectively.

The subject-wise scores for each \( n \)-shot learning are shown in Fig. 4. The differences between IR and AR scores are more pronounced here for individual subjects. It is to be noted that the subjects are tested on the same set of objects in both retrieval tasks, with no feedback in between. Since the learnt association does not change after the learning phase, we expect the retrieval scores to be the same. The difference suggests that the modality of the query factors into the strength of the association. Another possibility is the elimination of options for harder test cases, which may vary across subjects depending on their memory preference of one modality over the other.

4.1.2. Temporal Dynamics of Association Learning

For each exposure, we analyze the number of clicks for a sample termed as the number of listens per sample. The average number of listens per sample for every subject is shown in Fig. 5. From the figure, it is evident that the average number of listens per sample for the 1st exposure is significantly higher than...
that of the 2nd exposure for all subjects. This difference is observed between the 2nd and 3rd exposures as well. However, the difference between the average listens per sample in 2nd exposure and 3rd exposure is a lot lesser compared to the difference between first and second exposures.

We can speculate that a major chunk of the association learning happens during the 1st exposure, which is reinforced in the memory during the 2nd exposure. The average number of listens for the 3rd exposure is 1.375 which suggests that, for most classes, the subjects are merely confirming the association by hearing the audio once.

4.1.3. Analysing Human’s Correspondence Learning

Most of the human subjects participated in the experiment were able to learn audio-visual correspondence of unknown image and audio stimuli with more than 90% accuracy with just three time-separated exposures of the stimuli in 2 modalities. The retrieval accuracy is observed to increase significantly with two exposures than after the single exposure. The average accuracy is higher for three shot learning than for the single exposure. The second exposure helps embed this information in the memory during the 2nd exposure. The average number of listens per sample in 2nd exposure and 3rd exposure is a lot lesser compared to the difference between first and second exposures.

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4.2. Machine Results

The random sampling of negative points primarily from the large set of pretraining samples leads to variance in the model. We average the retrieval accuracy of the model trained using 5 random seeds. The mean and standard error of the accuracy is given in Fig 3.

4.2.1. Machine vs Human performance

The model’s retrieval accuracy is averaged over each n-shot as shown in Fig. 3. The model retrieval accuracy pattern is comparable to that of humans after n-shot learning. It follows a steady increasing trend in accuracy as n increases, with the IR accuracy consistently better than that of AR. It also outperforms humans in all cases, except for AR in one-shot learning.

4.2.2. One shot generalisation

The test results for generalisation from a single exposure are shown in Fig 6. Unseen query stands for the testing case where augmented variants of the query sample, different from those in the training, are used. Seen query stands for the testing case where the query sample is same sample used in training. The machine model has a significant improvement in performance for IR and AR on the seen queries. For humans, the scores appear more consistent with a minor improvement between the seen and unseen queries. This suggests that humans have a better ability to generalize to new samples even from a single exposure.

5. Conclusions

• With increase in the number of exposures to the stimulus, humans and machines learn the audio-visual correspondence with better accuracy.

• The time spent and number of times a subject listens to the audio at a particular exposure confirms that the major chunk of association learning happens in the first exposure of the audio-visual pair.

• This paper proposes a machine model which performs on par with the humans in audio-visual correspondence learning.

• Humans have a better ability to generalize to new samples even from a single exposure.
6. References


[14] “microsoft azure text-to-speech.”


