## E9 205 – Machine Learning for Signal Processing

Homework # 3 Due date: Oct. 14, 2019 (in class).

Analytical in writing and report for the coding part in writing/print submitted in class. Actual code alone in a single zip file with name "Assignment3\_FullName.zip" submitted by email to mlsp19.iisc@gmail.com Assignment should be solved individually without consent.

October 2, 2019

1. Kernel LDA Deepak has learnt about linear discriminant analysis in his course. In a job interview, he is asked to find a way to perform dimensionality reduction in nonlinear space. Specifically, he is given a set of N data points  $\{x_1, x_2, ..., x_N\}$  and a non-linear transformation  $\phi(x)$  of the data. When he is asked is to define LDA in the non-linear space, he defines the within-class and between-class scatter matrices for a twoclass problem as,

$$egin{array}{rcl} m{S}_B &=& (m{m}_2^\phi - m{m}_1^\phi) (m{m}_2^\phi - m{m}_1^\phi)^T \ m{S}_W &=& \displaystyle{\sum_{k=1}^2 \sum_{n \in C_k} \left[m{\phi}(m{x}_n) - m{m}_k^\phi 
ight] ig[m{\phi}(m{x}_n) - m{m}_k^\phi ig]^T} \end{array}$$

where  $\boldsymbol{m}_{k}^{\phi} = \frac{1}{N_{k}} \sum_{n \in C_{k}} \boldsymbol{\phi}(\boldsymbol{x}_{n})$  for k = 1, 2 and  $C_{k}$  denotes the set of data points belonging to class k. He also defines the Fisher discriminant as

$$J = \frac{\boldsymbol{w}^T \boldsymbol{S}_B \boldsymbol{w}}{\boldsymbol{w}^T \boldsymbol{S}_W \boldsymbol{w}}$$

where  $\boldsymbol{w}$  denotes the projection vector. He goes on to say that he can solve the generalized eigen value problem to find  $\boldsymbol{w}$  which maximizes the Fisher discriminant. At this point, the interviewer suggests that  $\boldsymbol{\phi}(\boldsymbol{x})$  can be infinite dimensional and therefore LDA suggested by Deepak cannot be performed. Deepak counters by saying that he could solve for the LDA using kernel function  $k(\boldsymbol{x}_i, \boldsymbol{x}_j) = \boldsymbol{\phi}(\boldsymbol{x}_i)^T \boldsymbol{\phi}(\boldsymbol{x}_j)$ . He goes on and shows that LDA can indeed be formulated in a kernel space and the projection of a new data point can be done using kernels (without computing  $\boldsymbol{\phi}(\boldsymbol{x})$ ). How would you have found these two solutions if you were Deepak ? (Points 20)

2. By definiton, a kernel function  $k(\boldsymbol{x}, \hat{\boldsymbol{x}}) = \boldsymbol{\phi}(\boldsymbol{x})^T \boldsymbol{\phi}(\hat{\boldsymbol{x}})$ . A neccessary and sufficient condition for defining a kernel function is that the Gram matrix  $\boldsymbol{K}$  is positive definite. Using

either of these definitions, prove the following kernel rules

$$egin{aligned} k(m{x}, \hat{m{x}}) &= ck_1(m{x}, \hat{m{x}}) \ k(m{x}, \hat{m{x}}) &= f(m{x})k_1(m{x}, \hat{m{x}})f(\hat{m{x}}) \ k(m{x}, \hat{m{x}}) &= m{x}^T m{A} \hat{m{x}} \ k(m{x}, \hat{m{x}}) &= k_1(m{x}, \hat{m{x}}) + k_2(m{x}, \hat{m{x}}) \ k(m{x}, \hat{m{x}}) &= k_1(m{x}, \hat{m{x}}) + k_2(m{x}, \hat{m{x}}) \ k(m{x}, \hat{m{x}}) &= k_1(m{x}, \hat{m{x}}) + k_2(m{x}, \hat{m{x}}) \end{aligned}$$

where  $k_1, k_2$  denote valid kernel functions, c > 0 is any scalar,  $f(\boldsymbol{x})$  is any scalar function and  $\boldsymbol{A}$  is symmetric positive definite matrix.

## (Points 10)

3. One-class SVM Let  $X = \{x_1, x_2, ..., x_l\}$  be dataset defined in  $\mathbb{R}^n$ . An unsupervised outlier detection method consist of finding a center a and radius R of the smallest sphere enclosing the dataset in the high dimensional non-linear feature space  $\phi(x)$ . In a soft margin setting, non-negative slack variables  $\zeta_j$  (for j = 1, ..., l) can be introduced such that,  $||\phi(x_j) - a||^2 \leq R^2 + \zeta_j$ 

The objective function in this case is to minimize radius of the sphere with a weighted penalty for slack variables, i.e.,  $R^2 + C \sum_{j=1}^{l} \zeta_j$  where C is a penalty term for allowing a trade-off between training errors (distance of points outside the sphere) and the radius of the smallest sphere.

- (a) Give the primal form Lagrangian and the primal constraints for the one-class SVM. (Points 5)
- (b) Find the dual form in terms of kernel function and the KKT constraints for the one-class SVM. What are the support vectors? Will support vectors change when C > 1 is chosen? Give a numerically stable estimate of R (Points 15)
- (c) For a new data point  $\boldsymbol{x}$ , how will we identify whether it is an outlier or not (using kernel functions) ? (Points 5)
- 4. Use the following data source for the remaining two questions leap.ee.iisc.ac.in/sriram/teaching/MLSP\_19/assignments/data/Data.tar.gz
  Implementing Linear SVMs - 15 subject faces with happy/sad emotion are provided in the data. Each image is of 100 × 100 matrix. Perform PCA to reduce the dimension from 10000 to K. Implement a classifier on the training images with linear kernel based support vector machine. One potential source of SVM implementation is the LIBSVM package
  - http://www.csie.ntu.edu.tw/ cjlin/libsvm/
  - (a) Use the SVM to classify the test images. How does the performance change for various choice of kernels, parameter C and  $\epsilon$ . How does the performance change as a function of K.
  - (b) Compare the SVM classifier with LDA classifier and comment on the similarity and differences in terms of the problem formulation as well as the performance.

(**Points** 15)

5. **Supervised Sentiment Analysis** - Download the movie review data (each line is a individual review)

 $http://www.leap.ee.iisc.ac.in/sriram/teaching/MLSP\_19/assignments/movieReviews1000.txt$ 

- a Split the data into two subsets. One for training (first 3000 reviews) and the other for testing (last 1000 reviews).
- b Use TF-IDF features and train PCA (using the training data) to reduce the data to 10 dimensions.
- c Train a SVM model. And check the performance on the test set in terms of review classification accuracy.
- d Compare different kernel choices linear, polynomial and radial basis function. Report the number of support vectors used and the classification performance for different kernel choices.

(Points 30)